

Math-6500 Partial Differential Equations Fall 2007
Assignment 5

Due Monday, November 12, by 4pm. PDEs of the first order

1. Write down an explicit solution for the initial-value problem

$$u_t + \mathbf{b} \cdot \nabla u + cu = 0, \quad x \in \mathbb{R}^n, t > 0, \quad u(x, 0) = g(x).$$

Here \mathbf{b} and c are constants and the gradient vector $\nabla u = (\partial u / \partial x_1, \dots, \partial u / \partial x_n)$ is the gradient vector.

2. Solve the problem

$$xu_x + u_y = 1, \quad x \in \mathbb{R}, y > 0, \quad u(x, 0) = \exp(x)$$

3. Use the method of characteristics to solve the problem

$$xu_x + (x + y)u_y = 1,$$

where $u(1, y) = y$ for $0 < y < 1$. Describe the region in the xy -plane over which the solution is uniquely determined.

4. (*F. John* 1.9.1) For the equation

$$u_x^2 + u_y^2 = u^2$$

find

- (a) The characteristic strips;
 - (b) The integral surfaces passing through the circle $x = \cos s, y = \sin s, z = 1$. (There are two surfaces).
 - (c) The integral surfaces passing through the line $x = s, y = 0, z = 1$. (There are two surfaces).
5. (Characteristics of the Hamilton-Jacobi equation as extremals of a variational problem). In class I considered a one-dimensional version of the following equation

$$F := \frac{\partial u}{\partial t} + H \left(x_1, \dots, x_n, t, \frac{\partial u}{\partial x_1}, \dots, \frac{\partial u}{\partial x_n} \right) = 0$$

(Hamilton-Jacobi equation). The characteristic equations have the form

$$\frac{dx_i}{dt} = H_{p_i}, \quad \frac{du}{dt} = -H + \sum_i p_i H_{p_i}, \quad \frac{dp_i}{dt} = -H_{x_i}$$

Setting

$$\frac{dx_i}{dt} = v_i, \quad \frac{du}{dt} = L$$

one can use the first $n + 1$ equations to express L as a function of $x_1, \dots, x_n, t, v_1, \dots, v_n$. Show then that

$$L_{v_i} = p_i, \quad L_{x_i} = -H_{x_i}.$$

This implies that

$$\frac{d}{dt} L_{v_i} - L_{x_i} = 0.$$

[These are the Euler-Lagrange equations for an extremal of the minimization problem

$$\int L \left(x_1, \dots, x_n, t, \frac{dx_1}{dt}, \dots, \frac{dx_n}{dt} \right) dt \rightarrow \min$$

(the least action principle); this problem is discussed in any book on analytical mechanics. See first four pages of Sec. 11.1 of *Guenther & Lee* about the Euler-Lagrange equations].

6. Consider the differential equation in the *divergence form*:

$$\frac{\partial R(u)}{\partial y} + \frac{\partial S(u)}{\partial x} = 0, \quad (\text{div})$$

where R and S are known functions. [Note that the left-hand side is the divergence of the vector (S, R) .] Define a weak solution $u(x, y)$ of (div) as a function for which the relation

$$\int \int (R(u)\phi_y + S(u)\phi_x) dx dy = 0 \quad (\text{integr})$$

holds for any function $\phi(x, y)$ of class C_0^∞ , i.e. for any function $\phi(x, y)$ that is infinitely differentiable and is zero everywhere except for a bounded set. (Relation (integr) follows formally from (div) through multiplication by ϕ and integration by parts.). Let $u(x, y)$ be C^1 in each of the two regions of the xy -plane separated by the curve $x = \xi(y)$. Show that if $u(x, y)$ is a weak solution then:

- (a) It is a solution of (div) in each of the two regions;
- (b) It satisfies the following jump relation across the curve $x = \xi(y)$:

$$\frac{S(u^+) - S(u^-)}{R(u^+) - R(u^-)} = \frac{d\xi}{dy}$$

You may need to use the Stokes formula

$$\oint_{\partial B} P dx + Q dy = \int \int_B \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy$$