

## Impulse and Momentum Change

Your goal today is to demonstrate that impulse  $J$  gives a momentum change  $\Delta p$ , that is

$$J \equiv \int_{t_i}^{t_f} F(t) dt = p_f - p_i \equiv \Delta p \quad (1)$$

We will closely follow the “regular” Physics I Activity 05, which relies on Activity 03 for calibrating the force probe and for determining the effect of friction. Please refer to these activities, posted at <http://www.rpi.edu/dept/phys/Courses/phys1/activities.htm>, for details.

The experiment is done with a cart on a track. You will impart momentum to the cart by pulling on it with a force probe, which records  $F(t)$ . The force probe is calibrated by hanging a known mass from it. A motion sensor will determine the initial and final velocity, which you combine with the cart mass to get  $\Delta p$ . As always, of course, you are to try to demonstrate that both sides of Eq. 1 are satisfied to within experimental uncertainties. Friction plays a part, and you are to include its effect in order to reduce the systematic uncertainty its neglect would introduce.

(1) Debug your setup and determine the frictional force  $f$  on the cart. See Activity 03. Give the cart a push, and let friction slow it down. Measure the acceleration  $a$  with a motion sensor, so  $f = ma$  where  $m$  is the mass of the cart.

(2) Calibrate the force probe. Again, see Activity 03. **LOGGERPRO** is apparently set up to do this automatically by hanging a known mass from it and choosing the “Calibrate” menu item. It will assume a linear response between zero and the mass you choose to hang. It seems that a good mass to choose is 52 g, but it would be a good idea to try a few different masses depending on the force you use to effect the momentum change.

(3) Connect the force probe to the cart, and give it a quick pull to make the cart move. (Let the cart move away from the motion sensor.) From the  $F(t)$  data, identify an “initial” and “final” time over which the force acts, and calculate the integral  $\int_{t_i}^{t_f} F(t) dt$ . The motion sensor will give you the initial - presumably zero - and final velocity of the cart, so you can determine the change in momentum.

(4) Take into account the impulse due to friction. That is, include the term  $f\Delta t$  in your calculation of the impulse. (We assume that friction is constant over the time  $\Delta t = t_f - t_i$ .) How big a correction does this make? Perhaps you can better see the extent to which this correction makes a difference by giving your cart a “pull” with larger and/or smaller force.