

Multiple Model Predictive Control of Hemodynamic Variables

An Experimental Study



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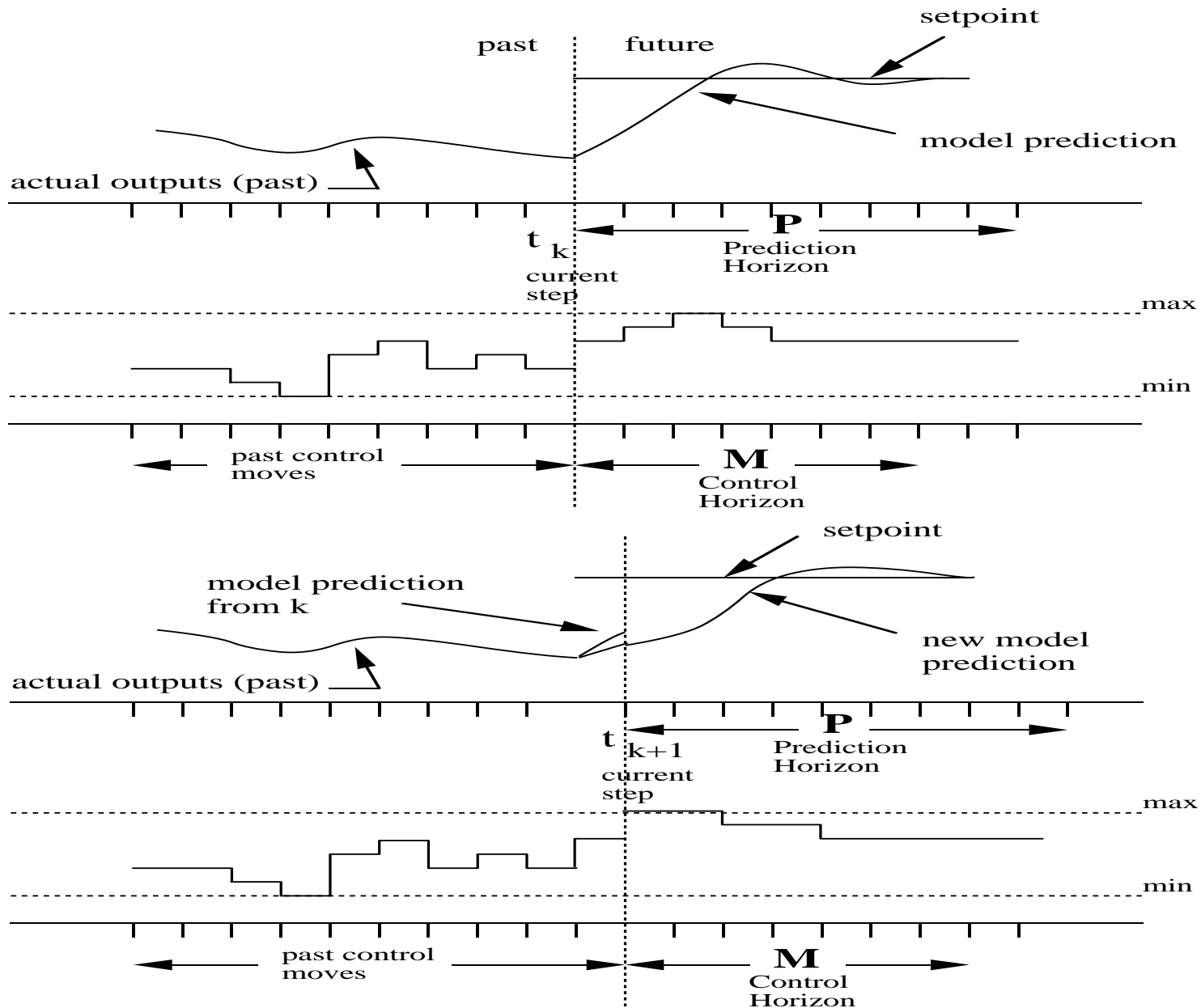
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Motivation

- Patients in critical care or surgery
- Typical clinical practice
 - ◆ manual regulation with drip IV
 - ◆ programmable pumps (open loop)
 - ◆ estimation of pharmacokinetics and pharmacodynamics
- State of the art
 - ◆ clinical trials of closed loop control of mean arterial pressure (MAP)
- Our objective
 - ◆ automated regulation of hemodynamic variables with physician "in the loop"
 - ◆ free-up physician to monitor difficult-to-measure variables

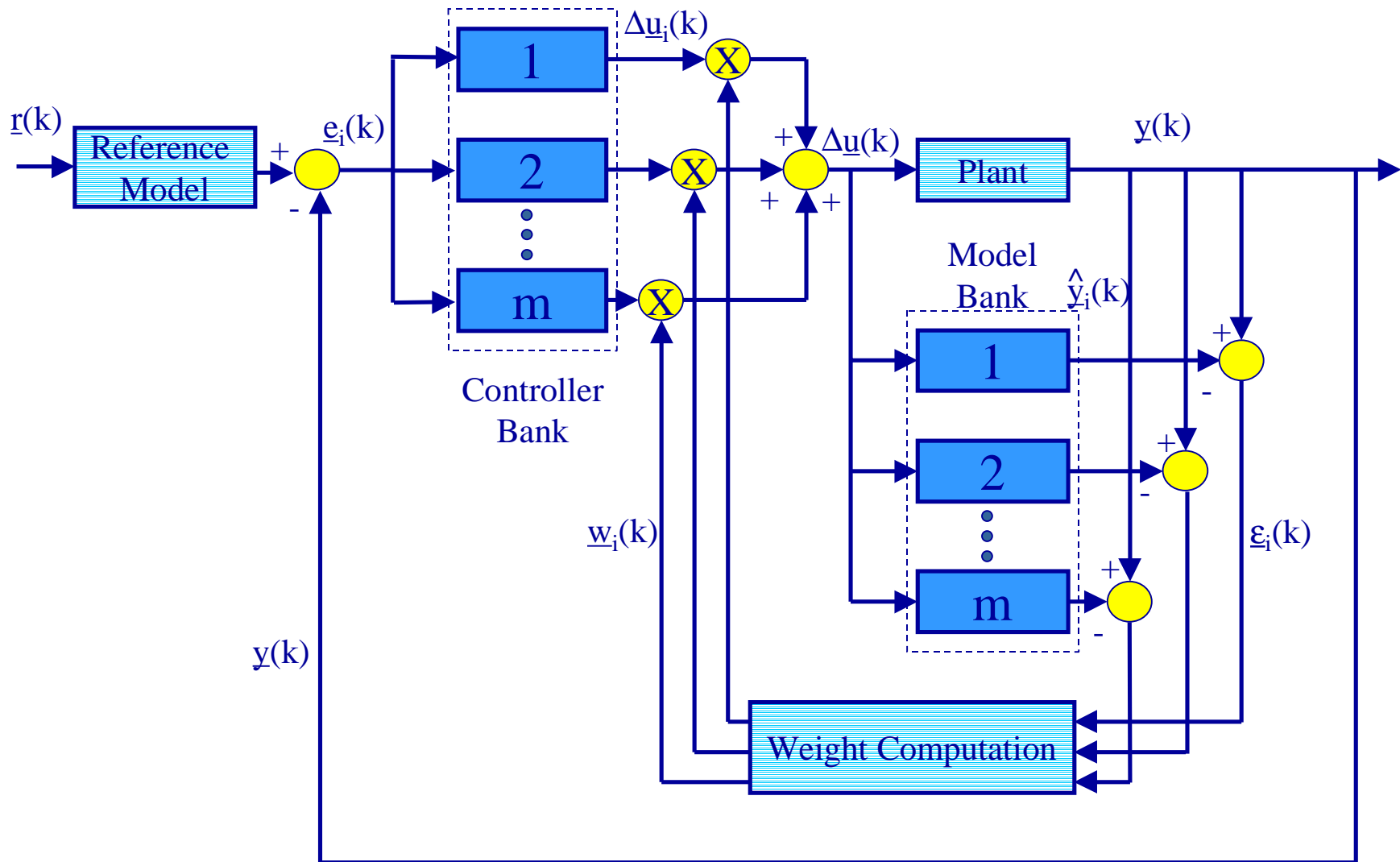
Problem Overview

- **Multivariable, nonlinear system**
 - ◆ regulation of mean arterial pressure (MAP), cardiac output (CO) using sodium nitroprusside (SNP), phenylephrine (PNP) and dopamine (DPM)
- **Inter- and intra patient variability**
 - ◆ requires on-line adaptation to patient conditions
- **Interactions from anesthetics**
- **Presence of constraint specifications**
 - ◆ inputs: drug dosage
 - ◆ outputs: setpoint specified as range, min or max
- **Use model predictive control (MPC) to handle constraints explicitly**

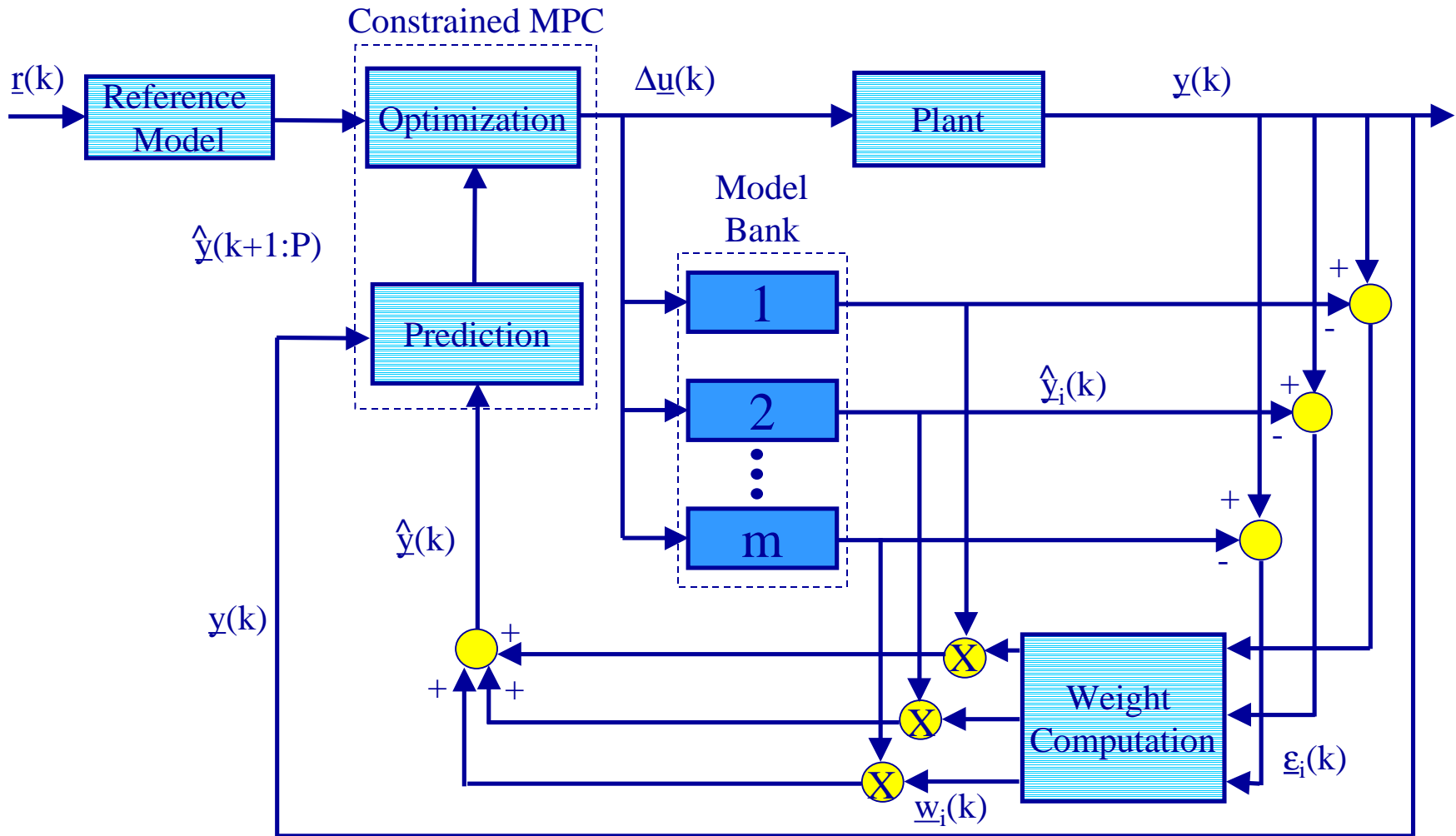


Model Predictive Control

Multiple Model Adaptive Control (MMAC)



Multiple Model Predictive Control (MMPC)



Weighting Scheme

Recursive Bayes Conditional Probability

$$p_{i,k} = \frac{\exp(-\frac{1}{2} \boldsymbol{\varepsilon}_{i,k}^T K \boldsymbol{\varepsilon}_{i,k}) p_{i,k-1}}{\sum_{j=1}^N [\exp(-\frac{1}{2} \boldsymbol{\varepsilon}_{j,k}^T K \boldsymbol{\varepsilon}_{j,k}) p_{j,k-1}]}$$

Weights

$$W_{i,k} = \frac{P_{i,k}}{\sum_{j=1}^N P_{j,k}} \quad \text{for } P_{i,k} > \delta$$
$$W_{i,k} = 0 \quad \text{for } P_{i,k} = \delta$$

- Probabilities & weights properly bounded
- Delta keeps model available for future use
- Steady state probabilities are 0 or 1

Model banks

	MAP			CO		
	Gain	Time Constants	Time Delays	Gain	Time Constants	Time Delays
SNP	-5 to -23	1.0 to 1.2	0.5	5 to 30	1 to 1.5	1 to 2
DPM	1 to 10	4 to 6	1 to 3	5 to 50	5 to 6	1 to 3

	MAP			CO		
	Gain	Time Constants	Time Delays	Gain	Time Constants	Time Delays
SNP	-4 to -35	1.2 to 2.0	.5 to 1.5	-1 to -9	1 to 2	0.5 to 1
DPM	1 to 9	5 to 7	2 to 4	5 to 57	5 to 7	1 to 5

Heart Contractility

- ↑ Dopamine (Inotropic)
- ↓ Halothane

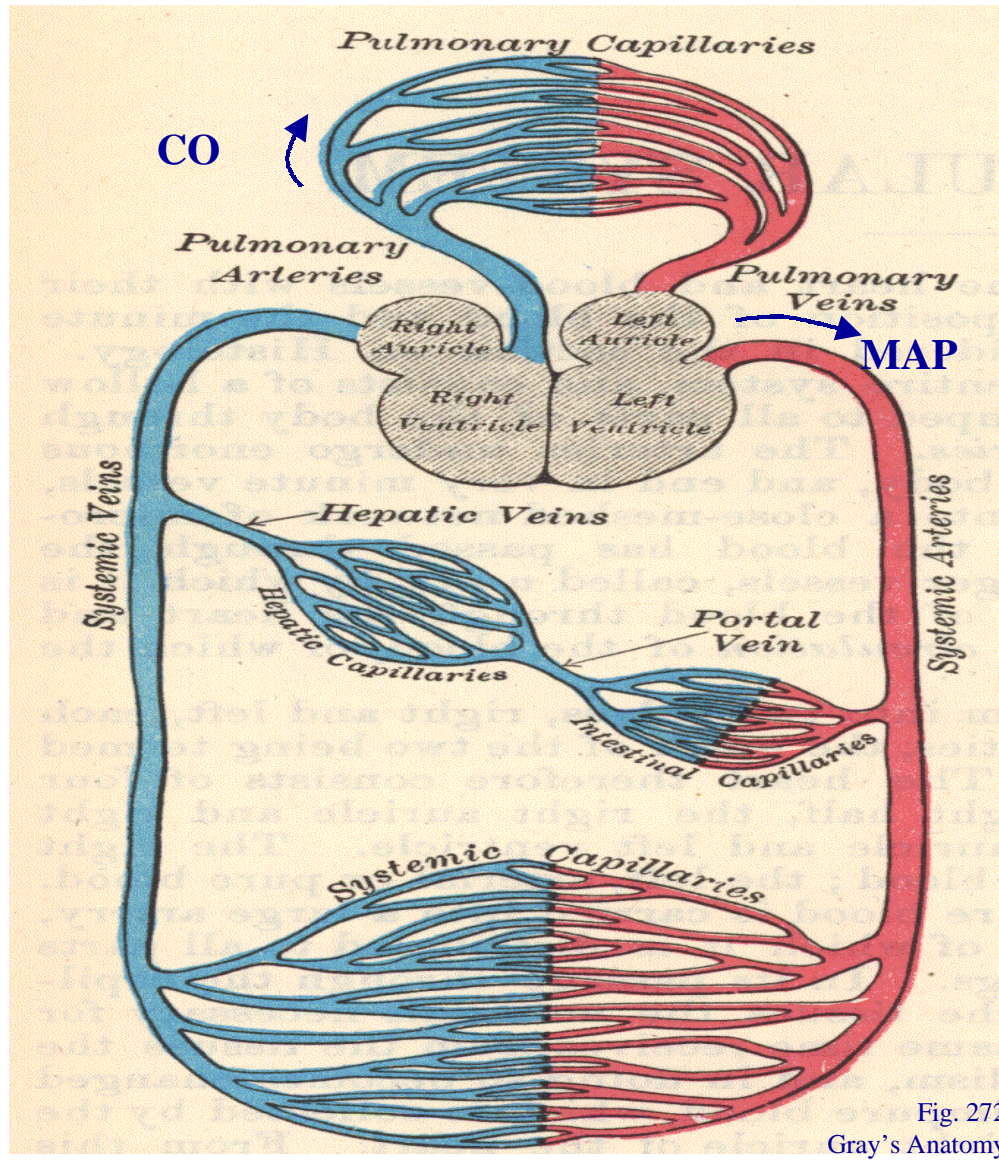
Venous Compliance

- ↓ Sodium Nitroprusside

Baroreceptor Reflex

- ↓ Halothane

■ Anesthetic
■ Cardiovascular
Drugs



Systemic Vascular

Resistance

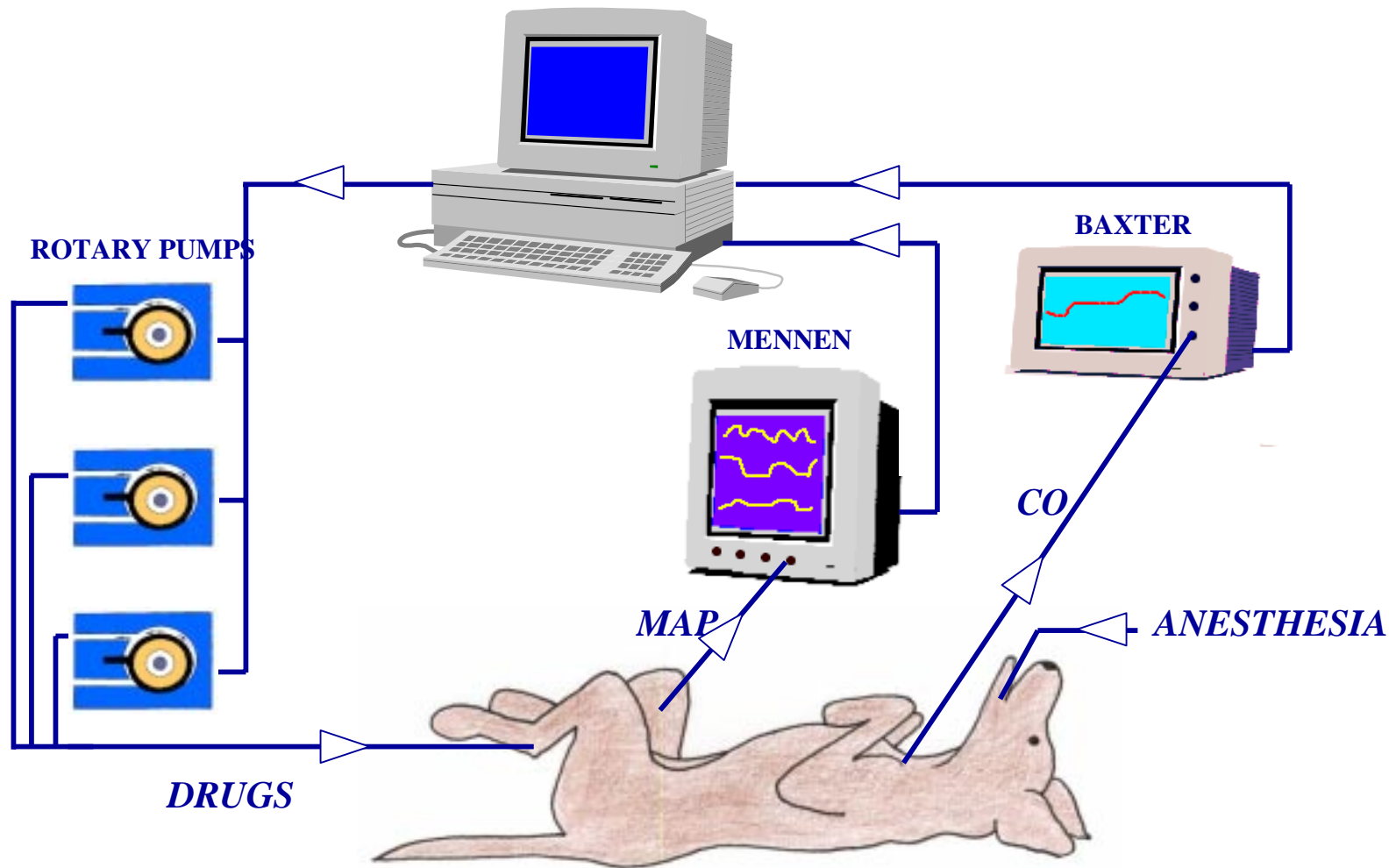
- ↑ Phenylephrine
- ↓ Sodium Nitroprusside
- ↓ Isoflurane
- ↓ Halothane
- ↓ Metabolites

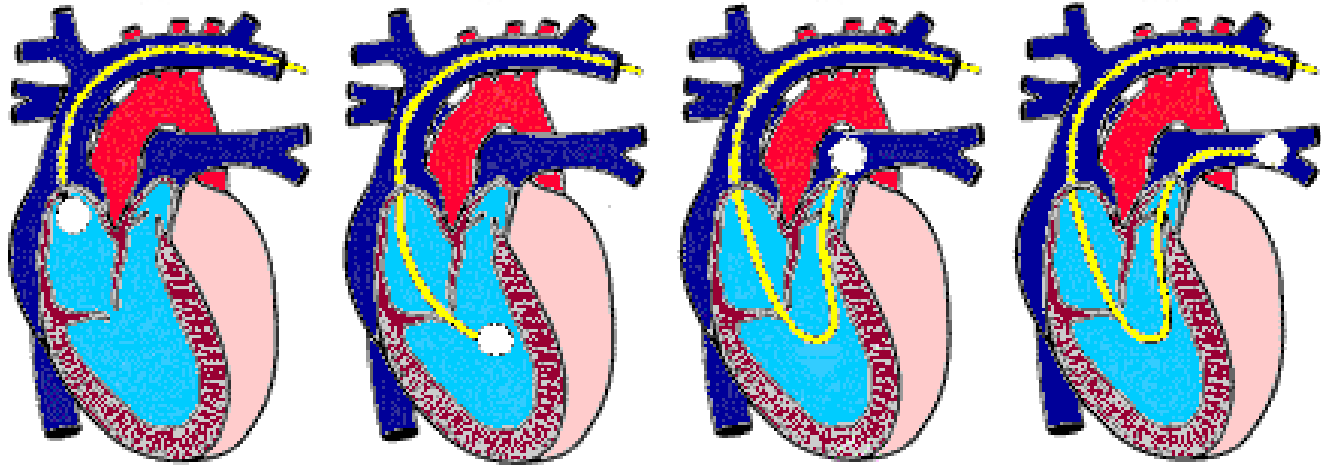
MAP-CO Relation

$$MAP = CO * (SVR - P_{RA})$$

Physiological Overview

Experimental Setup





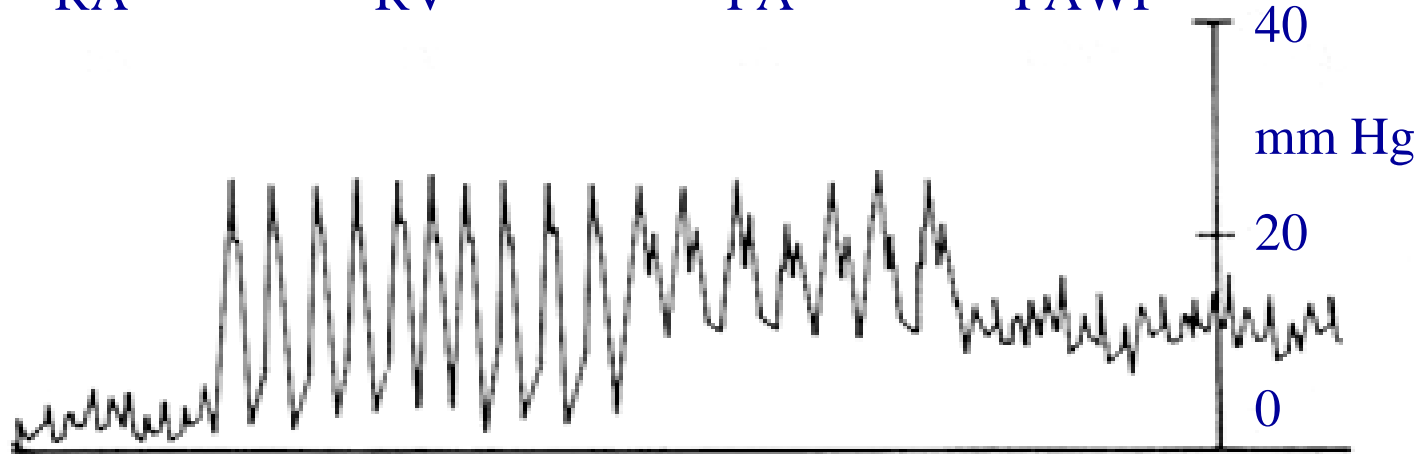
RA

RV

PA

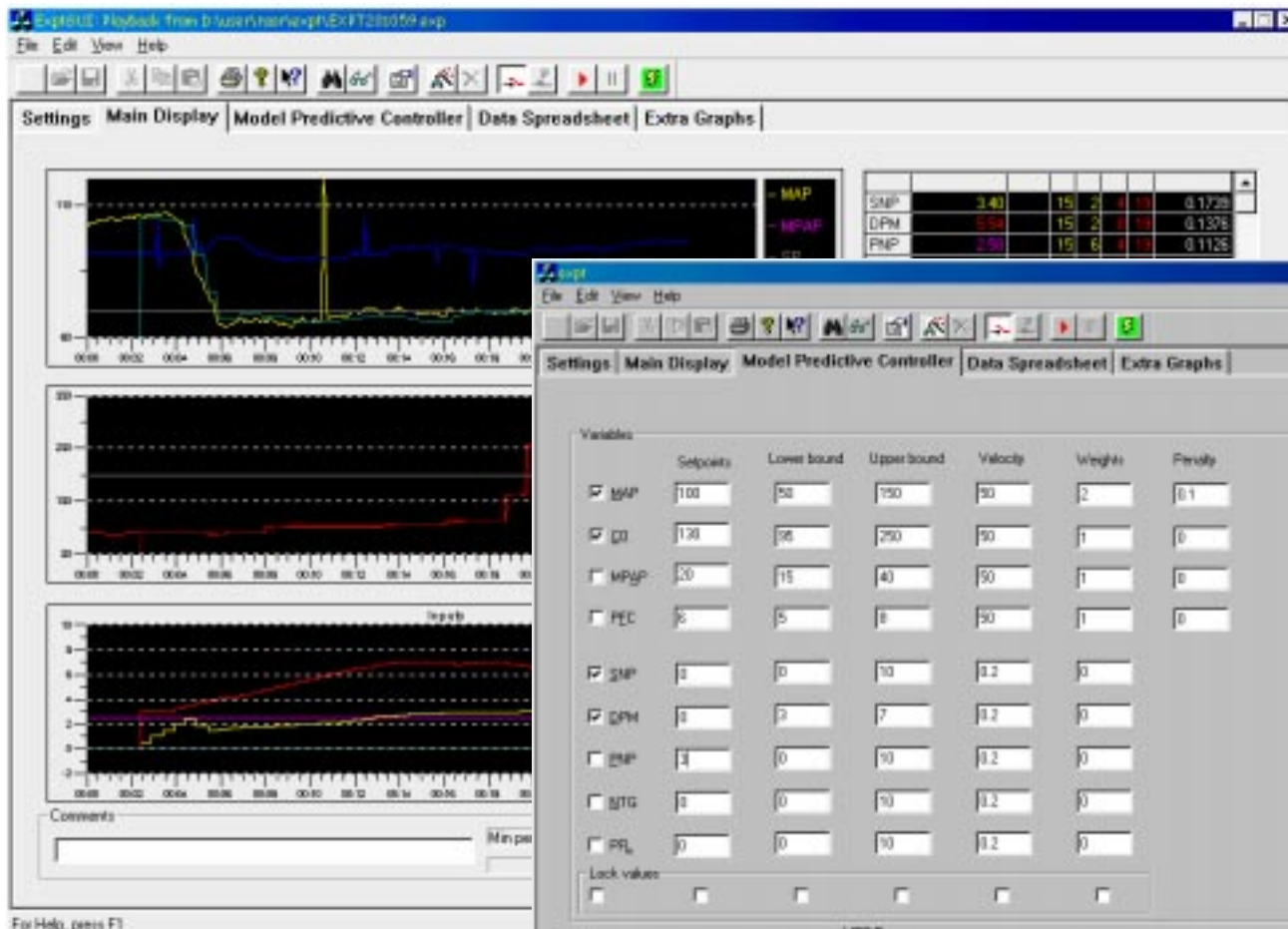
PAWP

EKG

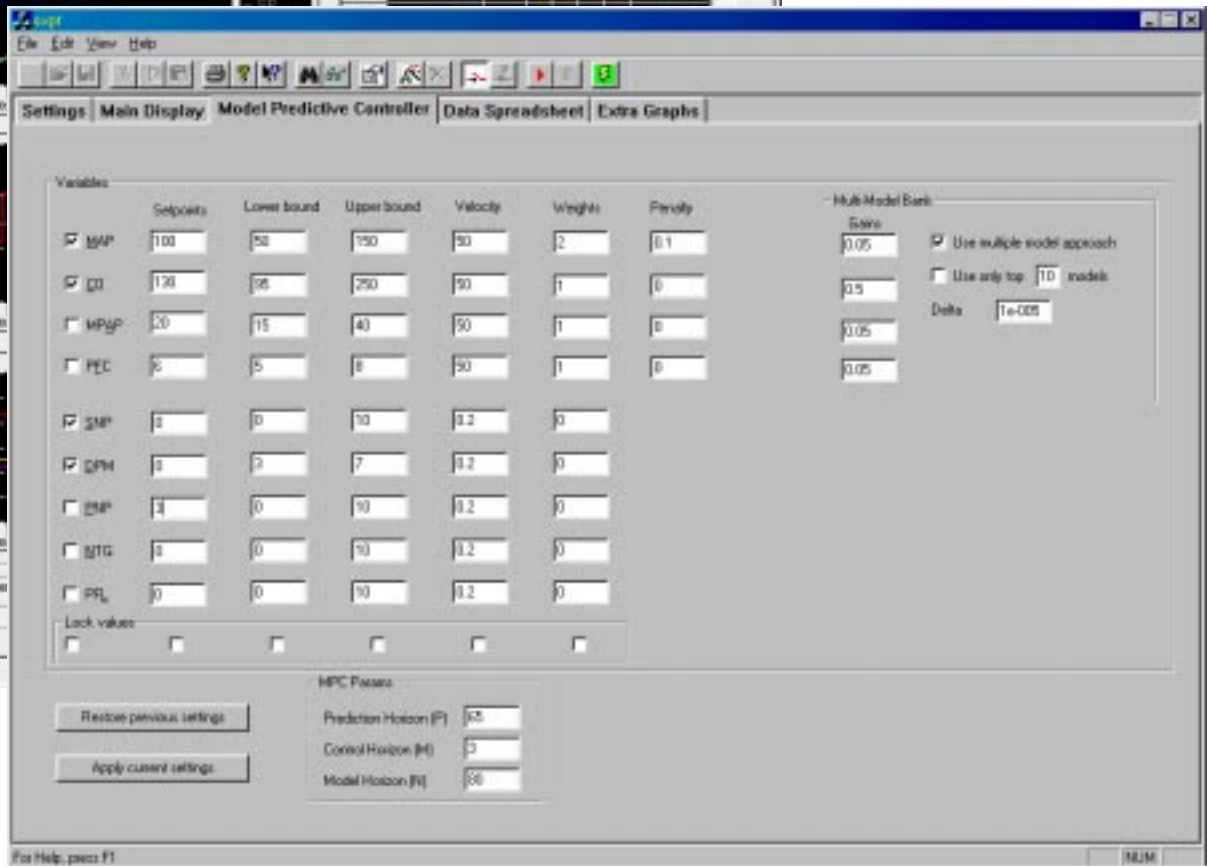


Swan-Ganz Insertion

User Interface



For Help, press F1



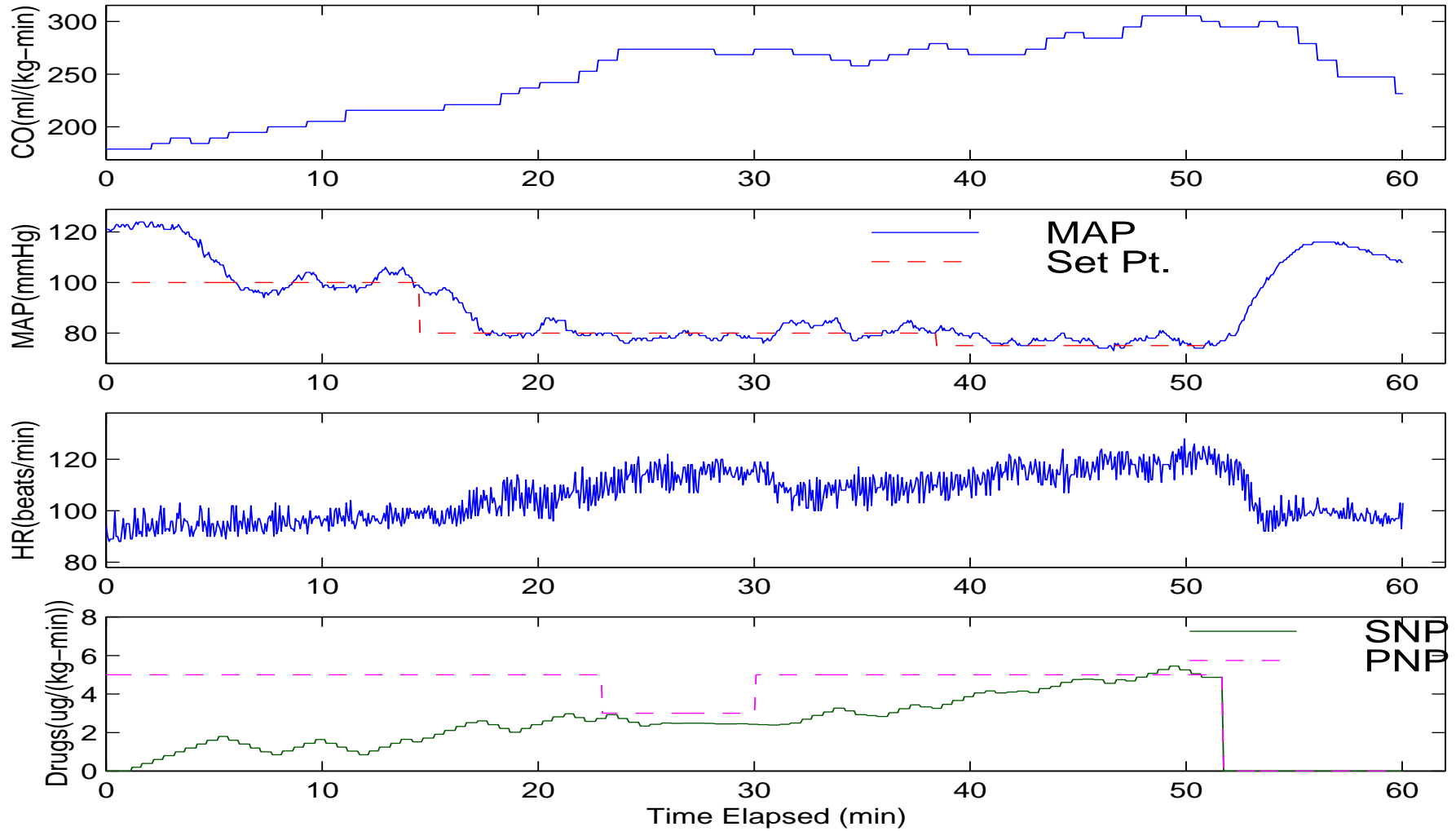
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MMPC Issues

- **Tuning of MPC**
- **Choice of model banks**
 - ◆ first order + time delay
 - ◆ number of banks to cover a given range of gains, time constants and time delays
- **Structure of the weighted bank**
 - ◆ model structure/order evolves
 - ◆ over-specification ?
- **Bayesian weighting**
 - ◆ designed to converge to one model
 - ◆ blending of models is preferred - detune convergence

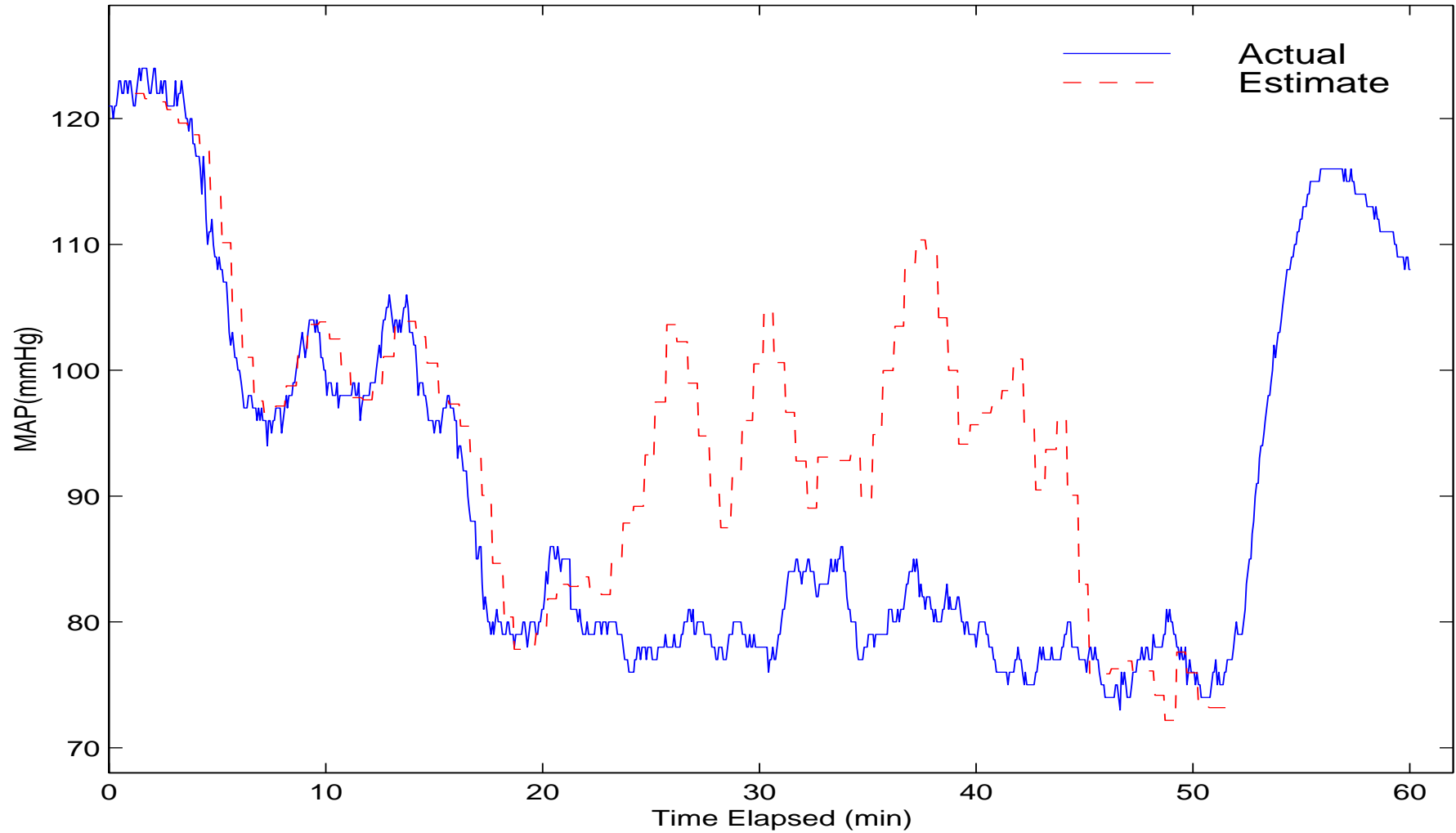
1. MAP Regulation (SISO)

MAP Controlled Via SNP with Isoflurane Oct. 26th 12:43

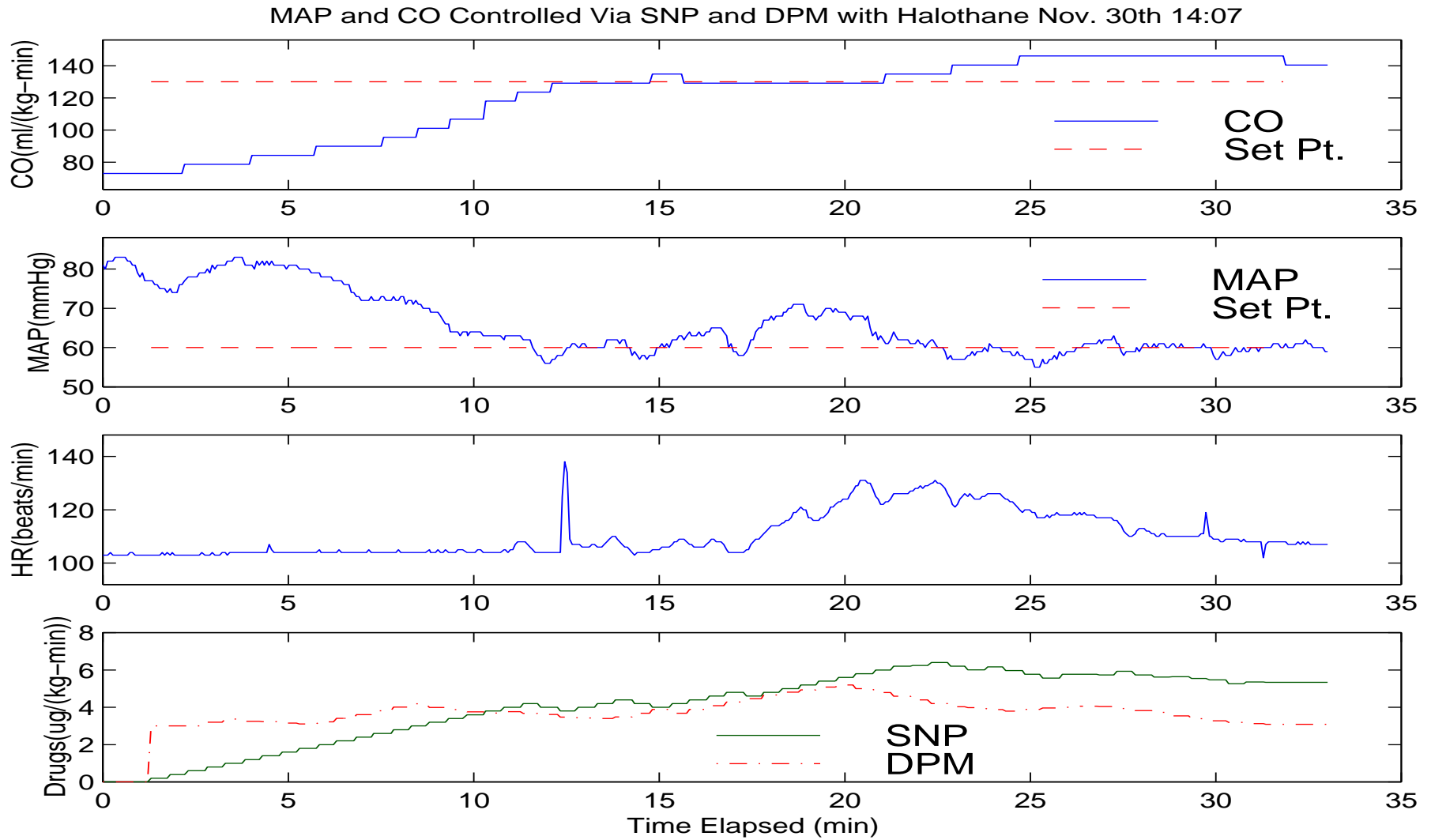


1. Weighted-Model Tracking

MAP Controlled Via SNP with Isoflurane Oct. 26th 12:43

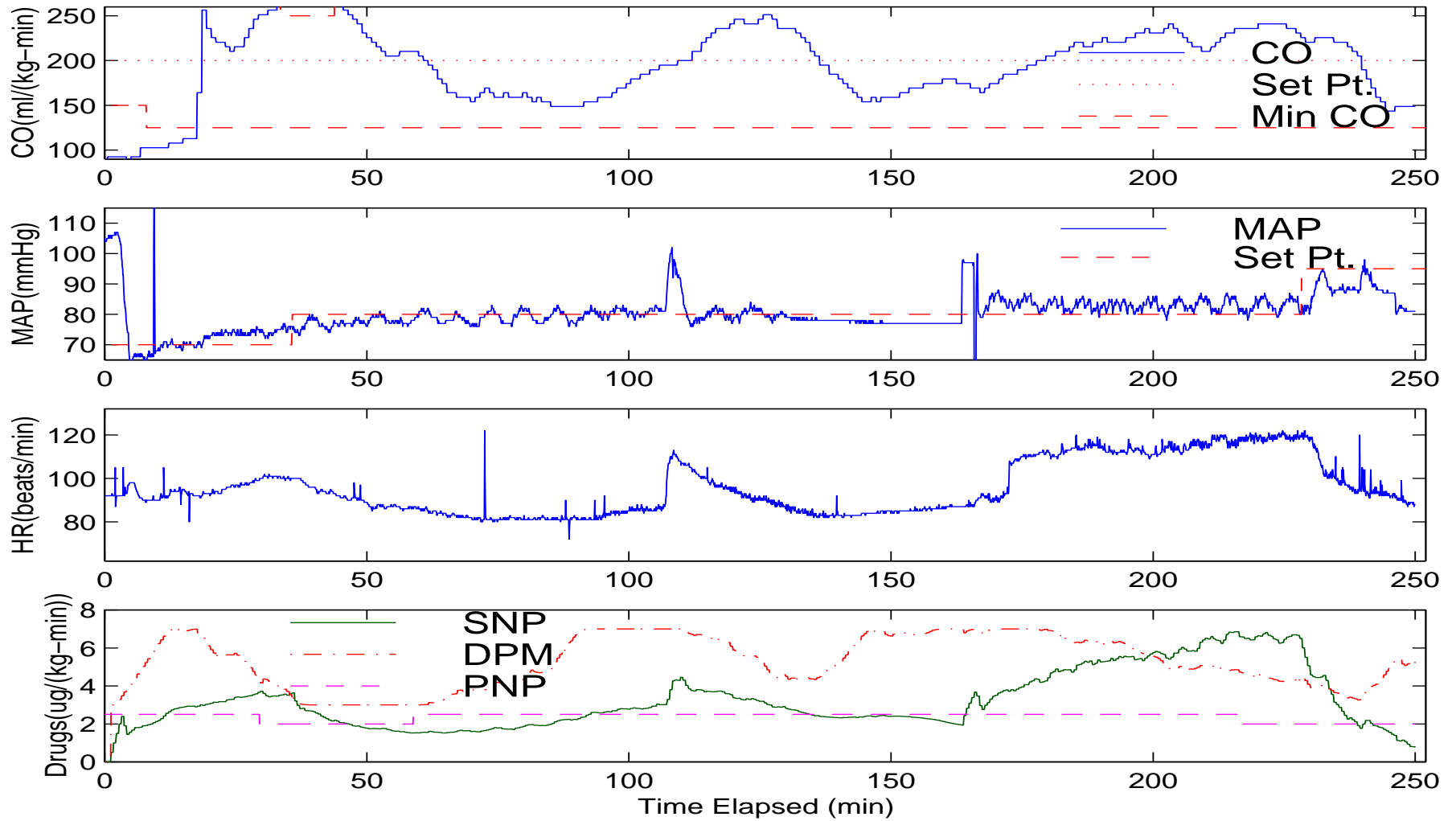


2. MAP and CO Regulation (MIMO)



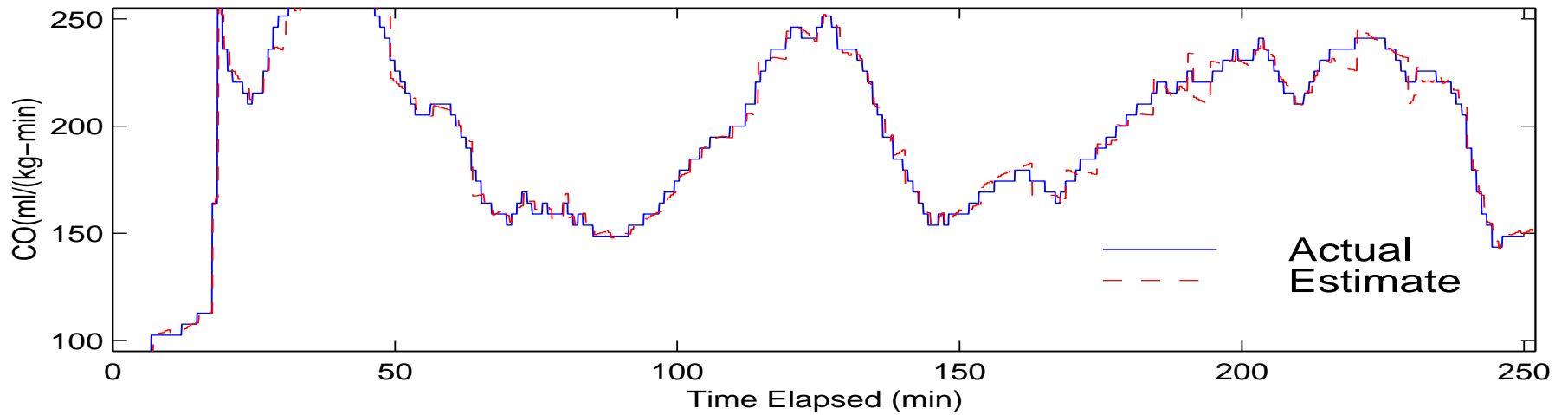
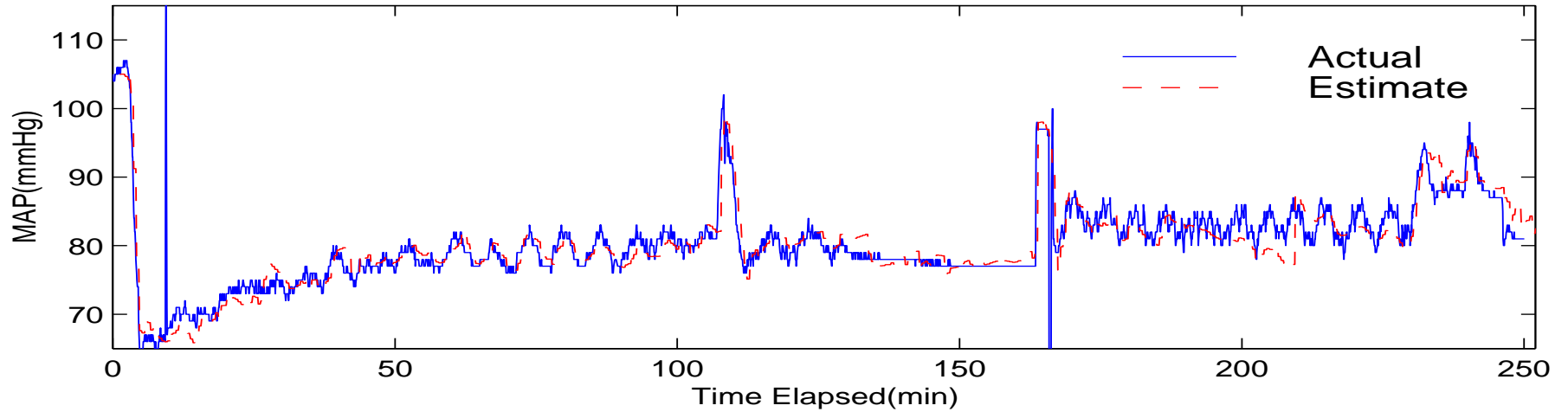
3. MAP and CO Regulation (MIMO)

MAP and CO controlled with SNP and DPM (under Halothane) May 20th 10:59



3. Weighted-Model Tracking

MAP and CO controlled with SNP and DPM (under Halothane) May 20th 10:59



Summary

- **Multiple model predictive control approach**
 - ◆ handling constraints
 - ◆ weighted model bank provides a flexible and bounded prediction model to handle inter- and intra patient variability
 - ◆ need for weighting schemes that are more conducive to blending
- **Future work**
 - ◆ experiments with induce congestive heart failure
 - ◆ develop weighting scheme more conducive to blending
 - ◆ develop MIMO model bank

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